26 Gripper EOAT Accessories



Hier bieten wir Ihnen alles an, was zu einem rationellen Greiferbau gebraucht wird:

GRIPPER CONSTRUCTION SOFTWARE

Description - Licence - Software





INFO

- The operation of this software is simple and intuitive. No prior knowledge, e.g. in operating a CAD system, is required. CAD - Grip works independently and without the combined use of standard CAD software. The user can configure their gripper offline. This eliminates the need to install software, which often leads to a high need for coordination with the IT department, especially in large companies. CAD - Grip is supplied on a USB stick.
- The application is started by an automatically running file. Installation on the company computer is therefore not necessary. "The application is child's play" The user imports the component to be gripped and moved. The gripper parts can then be systematically arranged from the versatile gripper kit using "drag and drop". At this point, the software supports the user, as the components are equipped with logical snap points that make sensible assignment easier. If the snap point is selected in the software, suitable components from the entire AGS product range are displayed as design proposals. The user receives valuable tips for alternative design solutions. The virtual assembly is checked and optimised. The arrangement of the appropriate gripper components is fully automatic.
- The screen shows whether the component corresponds to the automation solution. Ordering errors are therefore excluded. This applies in particular to the actual assembly of the gripper components in practice. Once the configuration is complete, the parts list is exported to the AGS customer portal and an online order can be triggered.
- The user can also export their configuration from the system. The appropriate format is available to the user for the CAD software used, e.g. Inventor, Autocad, Solidworks, Proengineer or Catia.
- AGS also provides important detailed information with the software. For example, the weight of the selected components is automatically added together and shows the user the total weight of the robot hand. Once a solution has been developed, it can be reproduced at any time and can therefore be used by different users. The documentation can be exported to a PDF file.
- You can obtain the software without the licence file via the link "Download Software". The required licence file will be sent to you by e-mail after submission and signing of the licence agreement (also as a download). This test licence is valid for 6 months.
- Important.
- Import of article data If possible use *.obj files – not larger than 100Mb.
- The file name must not contain spaces.

DESIGNATION	ITEM NO.
CADGrip 2.2	1-99-96-00-00-CGR