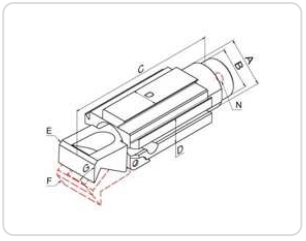
DESIGNATION	ITEM NO.	A	B	C	D	E	M	N	WEIGHT
GFI-20-95-P	1-65-02-08-00-GFI	20	M17×1	58	P13	P13	80N	M5	0.068Kg
GFI-30-95-P	1-65-04-08-00-GFI	30	M27×1	78	P22	P22	200N	G1/8	0.156Kg

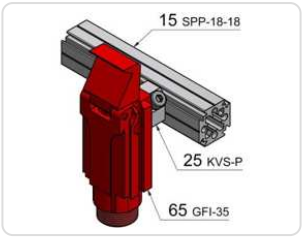
Legend: F = Finger extended G = maximum opening angle H = Basic finger position M = gripping force (at 6 bar) Gripping force 10N = 1kg N = Air connection

GRIPPER FINGER PRISM

GFI-35 Gripper Finger 35°







ADVANTAGES

- V1 -Query (fingers in and out folded) using C-slots-
- Cylinder sensor ZYS-3,7-.. possible, no sensor holder required
- V2 - Thread for extension tube VLS
- available as standard
- V3 - Clamping via prism, therefore no jamming of the
- piston as with round gripper fingers possible

REMARK

- Operating principle: Single-acting
- Operating pressure: 6 bar, use filtered and dried
- air

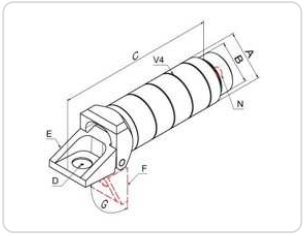
DESIGNATION	ITEM NO.	A	B	C	D	M	N	WEIGHT
GFI-20-35	1-65-02-04-00-GFI	20	M17×1	73	P13	45N	M5	0.069Kg
GFI-30-35	1-65-04-04-00-GFI	30	M27×1	102	P22	140N	G1/8	0.167Kg

Legend: E = Basic finger position F = Finger extended G = maximum opening angle M = gripping force (at 6 bar) Gripping force 10N = 1kg N = air connection

GRIPPER FINGER ROUND

GFI-95-E Gripper Finger 95° Easy





ADVANTAGES

- V1 - very short design
- V2 - favourable gripper finger
- V3 - various mounting options
- V4 - marking aid every 10 mm on the shaft for
- easy adjustment
- V5 - pre-centred for Easy DRP-X-E-G pressure plate

REMARK

- Operating principle: Single-acting
- - Extension thread for extension tube VLR
- - GFI-14-95-E query option on request, for
- GFI-20-95-E and GFI-30-95-E already available as standard
- Operating pressure: 6 bar filtered and dried
- air

DESIGNATION	ITEM NO.	A	B	C	D	M	N	WEIGHT	X
GFI-14-95-E	1-65-00-10-00-GFI	14	M12×1	55	4	20N	M5	0.02Kg	DRP-10-X-E-G
GFI-20-95-E	1-65-02-10-00-GFI	20	M17×1	83	5	40N	M5	0.049Kg	DRP-16-X-E-G
GFI-30-95-E	1-65-04-10-00-GFI	30	M27×1	98	2×5	125N	G1/8	0.143Kg	DRP-16-X-E-G

Legend: D = pre-centred for Easy DRP-X-E-G pressure plate Ø through-hole for DRP-X-E-G E = basic finger position F = finger extended G = maximum opening angle M = gripping force (at 6 bar) Gripping force 10N = 1kg N = air connection X = suitable for DRP-X-E-G