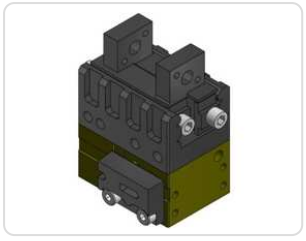
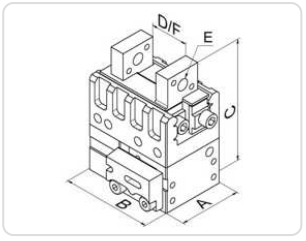
DESIGNATION	ITEM NO.	A	B	C	D	I	L	M	N	O	WEIGHT
PAG-R-4-25-LC	1-60-98-34-00-PAG	42	8	10	13	25	3	20N	21N	M5	0.156Kg
PAG-R-4-40-LC	1-60-98-38-00-PAG	62	12	12	16	40	4	86N	90N	M5	0.401Kg

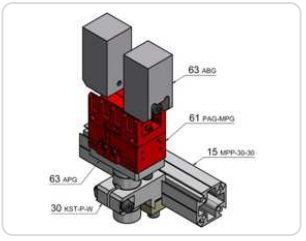
Legend: C = Jaw closed D = Jaw open I = Piston diameter L = Opening stroke per jaw M = Gripping force external gripping N = Gripping force inside gripping Holding force per jaw (30 mm lever arm, 5 bar) Gripping force 10N = 1kg O = Air connection

PARALLEL GRIPPER SCHUNK

PAG-MPG Parallel Gripper SCHUNK







ADVANTAGES

- V1 - Robust design
- V2 - Query gripper open/closed possible
- V3 - Centring via centring bushing between
- parallel gripper PAG and adapter APG-MPG-P

REMARK

- Operating principle: double-acting
- Operating pressure: use 6 bar filtered and dried
- air
- Fastening option using APG-MPG-P
- PAG-16: Lateral scanning with 2 sensors
- IN3-S-M8-PNP open/closed
- PAG-20: Lateral scanning with 2 sensors
- INS-4-2000 open/closed
- PAG-25/MPG-plus25 to PAG-64/MPG-plus64:
- Query with teachable sensor ZYS-TE-3.8-3-500-S
- Order inductive sensors
- separately
- Use of a freely programmable position
- sensor with evaluation electronics POS possible,
- (PAG-40 to -64 in standard version and PAG-20
- to -32 special)

DESIGNATION	ITEM NO.	A	B	C	D	E	F	L	M	N	WEIGHT	X
PAG-16/ MPG-plus 16	1-60-80-00-00-PAG	13	16	29	10	M3	7	1,5	20N	M2,5	0.038Kg	INS-3-S-M8-PNP
PAG-20	1-60-80-02-00-PAG	16	20	33	13	M4	9	2	25N	M3	0.038Kg	INS-4-2000
PAG-25 / MPG-plus 25	1-60-80-04-00-PAG	18	26	35	17	M4	11	3	35N	M3	0.056Kg	ZYS-TE
PAG-32	1-60-80-06-00-PAG	22	32	44	22	M5	14	4	80N	M5	0.114Kg	ZYS-TE
PAG-40	1-60-80-08-00-PAG	26	40	52	28	M5	16	6	135N	M5	0.196Kg	ZYS-TE
PAG-50 / MPG-plus 50	1-60-80-10-00-PAG	30	50	60	34	M6	18	8	215N	M5	0.333Kg	ZYS-TE
PAG-64	1-60-80-12-00-PAG	35	64	72	44	M8	24	10	300N	M5	0.6Kg	ZYS-TE

Legend: D = jaws moved apart (open) F = retracted (closed) jaws L = stroke per gripper jaw M = Closing force per jaw (20 mm lever arm, 6 bar) Gripping force 10N = 1kg N = Air connection X = inductive sensor