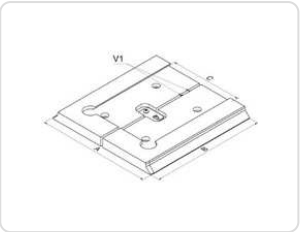
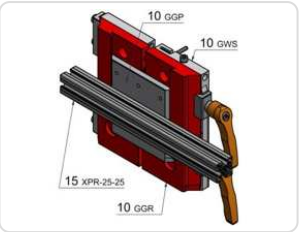
SQUARE MANUAL

GGR Base Plate Reduction







ADVANTAGES

- V1 - Design improvement: spring-mounted and
- guided for the best possible contour adaptation
- V2 - simple reduction option
- V3 - small gripper base plate GGP to larger
- Quick-change gripper system GWS

REMARK

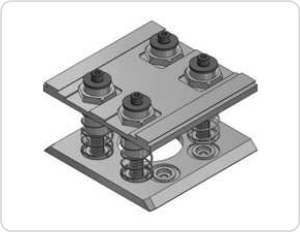
- Material = aluminium

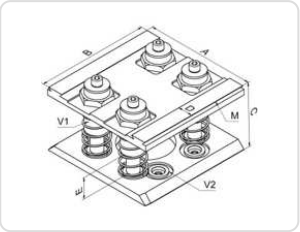
DESIGNATION	ITEM NO.	A	B	C	O	WEIGHT	X
GGR-1-0	1-10-12-50-00-GGR	100	100	60	GGP-0	0.162Kg	GWS-1
GGR-2-1	1-10-12-52-00-GGR	160	160	100	GGP-1	0.431Kg	GWS-2
GGR-3-2	1-10-12-54-00-GGR	250	250	160	GGP-2	1.24Kg	GWS-3

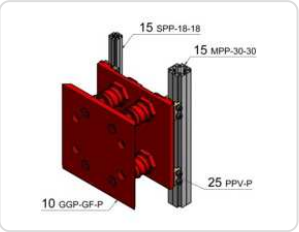
Legend: O = suitable for gripper base plate GGP..... X = suitable for gripper changing system GWS.....

SQUARE MANUAL

GGP-GF-P EOAT Base Plate spring loaded with Prism







ADVANTAGES

- V1 - Ball guides
- V2 - Profile holder 90° rotatable

REMARK

- GGP-GF-P should be used instead of spring-loaded gripper arm GGD or GGV
- if more than 10 of these are used
- Material = aluminium
- The illustration above shows our spring-loaded gripper base plate
- with prisms GGP-2-GF-P22-2

OPTION

- - Stop cylinder for locking
- - Query profile holder spring-loaded

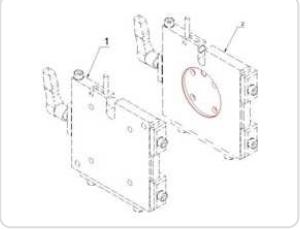
DESIGNATION	ITEM NO.	A	B	C	D	E	F	K	L	M	WEIGHT	X
GGP-1-GF-P13-2	1-10-11-60-00-GGP	100	100	50	P13	20	2	7kg	2	SPP	0.567Kg	GWS-1
GGP-2-GF-P22-2	1-10-11-64-00-GGP	160	160	85	P22	30	2	16kg	4	MPP	0.567Kg	GWS-2
GGP-3-GF-P22-3	1-10-11-68-00-GGP	250	250	85	P22	30	3	25kg	4	MPP	0.567Kg	GWS-3

Legend: E = Stroke F = Number of prisms K = Handling weight as guide value (directly on the quick-change system) Holding force 10N = 1kg L = Number of guide shafts M = suitable for profile .... X = suitable for gripper changing system GWS.....

SQUARE MANUAL

BAR Hole Pattern Adaptation to Robot





REMARK

- Drilling pattern variant 1 (BAR-E)
- Simple version with countersunk holes for mounting
- to robot flange

DESIGNATION	ITEM NO.	A	B
BAR-01-0-1-E	1-10-99-02-00-BAR	-01,-0,-1	ADP-1-P
BAR-01-0-1-K	1-10-99-02-02-BAR	-01,-0,-1	ADP-1-P