10.0 Gripper / EOAT Quick Change

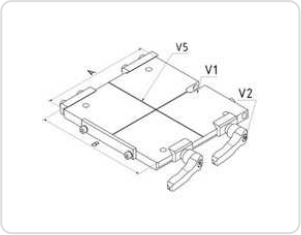


Gripper changing systems are used to connect grippers to handling devices or robots mechanically or even electrically or pneumatically. These can be controlled manually or automatically / pneumatically.

SQUARE MANUAL

GWS manual gripper changing system







ADVANTAGES

- V1 – Mechanical locking on sizes 1 – 2 – 3 also serves as an anti-rotation device for the GGP base plate
- V2 – The clamping levers are used for tool-free clamping of the GGP base plates. All GWS sizes are equipped with them.
- V3 - Simple gripper change
- V4 – 100% reproducible gripper position
- V5 – for easy attachment of the drilling template
- V6 – suitable for articulated and linear robots
- V7 – compatible with other manufacturers
- V8 – With the appropriate GGP gripper base plates, there is no need to take mounting holes for handling into account.

REMARK

- The GWS gripper changeover system allows you to drastically reduce your robot set-up times.
- The illustration above shows our GWS-3 gripper changeover system

DESIGNATION	ITEM NO.	A	B	C	H	O	WEIGHT	X
GWS-01	1-10-10-02-00-GWS	40	40	1	2,5Kg	1	0.148Kg	GGP-01
GWS-0	1-10-10-04-00-GWS	60	60	1	5Kg	1	0.202Kg	GGP-0
GWS-1	1-10-10-06-00-GWS	100	100	1	10Kg	1	0.418Kg	GGP-1
GWS-2	1-10-10-08-00-GWS	160	160	2	20Kg	1	1.063Kg	GGP-2
GWS-3	1-10-10-10-00-GWS	250	250	2	40Kg	1	3.184Kg	GGP-3

Legend: C = Number of clamping levers H = Handling weight as a guide value (directly on the quick-change) Holding force 10N = 1kg O = Material 1=Aluminium X = suitable for gripper base plate GGP ...